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Talk Abstract

In the IntellIoT Project (https://intelliot.eu/), we used W3C WoTTD for integrating Web-enabled industrial devices and Autonomous Agents within Multi-agent Systems

We successfully deployed two use cases: Autonomous Agriculture and Industrial Manufacturing



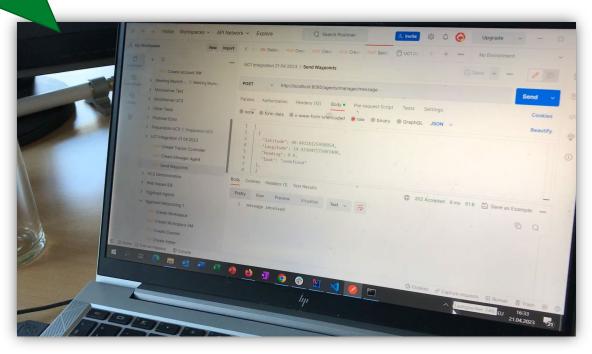
An **autonomous agent** drives a tractor **through W3C WoTTD**

Things expose WoTTDs (tractor controller, waypoint service, AI service, journaling service, human-in-the-loop service,...)

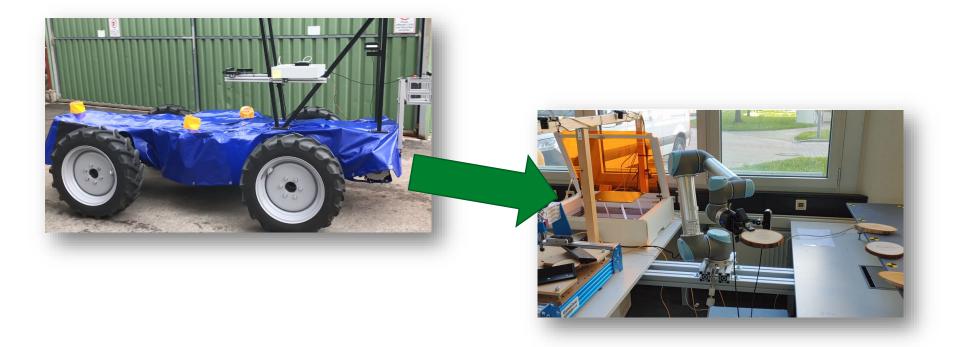
TDs are exposed via yggdrasil, a platform for agents and artifacts

TDs are discovered by a **no-code development environment.** A domain expert **programs an agriculture agent** to achieve operator goals

An **operator issues goals** ("Harvest field 5") at run time using a domain-specific interface



All IntellioT TDs: https://github.com/Interactions-HSG/example-tds/tree/intelliot/tds Tractor TD: https://github.com/Interactions-HSG/example-tds/blob/intelliot/tds/tractor_controller.ttl Example TD on yggdrasil: https://yggdrasil.interactions.ics.unisg.ch/environments/61/workspaces/102 Paper on no-code Development Environment (EMAS 2022): https://emas.in.tu-clausthal.de/2022/papers/paper3.pdf Extended abstract on architecture (AAMAS 2023): https://www.alexandria.unisg.ch/269570/



An **autonomous agent** manages a robot **through W3CWoTTD**

Things expose WoT TDs (robot controller, engraver, grabspot service, journaling service, human-in-the-loop service,...)

TDs are exposed via yggdrasil, a **platform** for agents and artifacts

TDs are discovered by a **no-code development environment.** A domain expert **programs a manufacturing agent** to achieve operator goals

An **operator issues goals** ("Engrave the text IntellIoT at location ×/y") at run time using a domain-specific interface

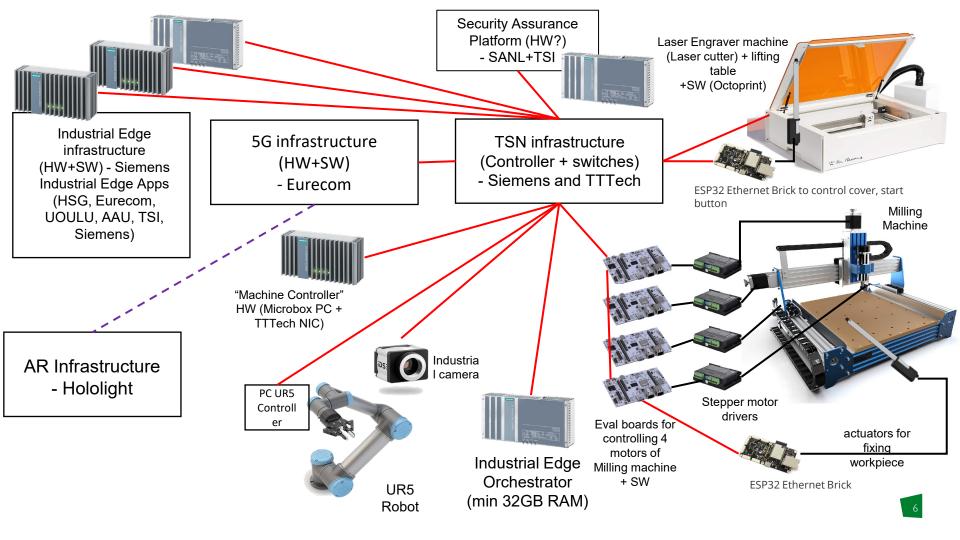
IntellioT

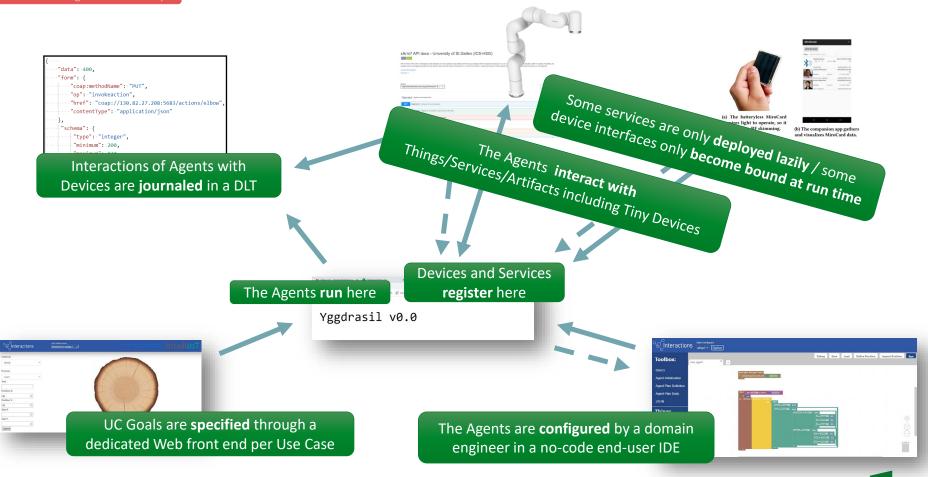
UC 3 - Manufacturing Scenario 1 - Collaboration Scenario 2 - Human in the Loop

Mid-term Review Meeting

17 May 2022

All IntellioT TDs: https://github.com/Interactions-HSG/example-tds/tree/intelliot/tds Robot TD: https://github.com/Interactions-HSG/example-tds/blob/intelliot/tds/uc3_robot.ttl Example TD on yggdrasil: https://yggdrasil.interactions.ics.unisg.ch/environments/61/workspaces/102 Paper on no-code Development Environment (EMAS 2022): https://emas.in.tu-clausthal.de/2022/papers/paper3.pdf Extended abstract on architecture (AAMAS 2023): https://www.alexandria.unisg.ch/269570/







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I cover these core components and approaches:

- I. Management of W3C WoTTDs in the Yggdrasil Hypermedia MAS Infrastructure
- 2. W3CWoTTD-based No-Code Development for Multi-agent Systems
- 3. W3CWoTTD Negotiation for lazy deployment and binding of edge services
- 4. W3C WoT TD-based Journaling of Agent-Artifact Interactions
- 5. W3C WoT TDs in the context of Affordance Theory



Enable **Decoupling**!

Enable Autonomy!

Aspect #1: Management of W3C WoTTDs in the **Yggdrasil Hypermedia MAS Infrastructure**

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Yggdrasil v0.0

https://www.alexandria.unisg.ch/256718/

- Supports creation of Hypermedia Multi-Agent Systems following the JaCaMo meta-model
- Supports the execution of computational artifacts, allows agents to instantiate artifacts, exposes HTTP interfaces for interacting with the artifacts, and generates W3CWoTTDs for the instantiated artifacts
- Yggdrasil-internal artifacts are complemented by W3C WoTTDs for **external devices or services**
- Resulting hypermedia environment is represented in RDF
- Infrastructure is compatible with a search engine for the W3CWoT

https://link.springer.com/article/10.1007/s00779-020-01415-1

Yggdrasil can be a blueprint for W3C WoTTD-based systems that include Autonomous Agents

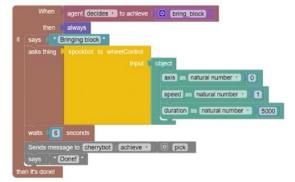
https://yggdrasil.interactions.ics.unisg.ch/environments/61

Aspect #2:W3CWoTTD-based No-Code Development for Multi-agent Systems

- W3CWoTTD-based visual programming for agents (AgentSpeak language)
- Configure and deploy Hypermedia Multi-agent Systems (extended to MAS organizations)
- Block language based on Blockly. Functional blocks are **automatically generated** from W3C WoTTDs
- Web-based IDE fetches W3C WoTTDs from Yggdrasil and generates functional blocks
- Configured agents are **deployed** to Yggdrasil
- Agent behaviors can be implemented against W3C WoTTD affordances while **resolving protocol binding only at run time**

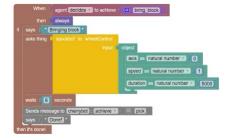
This Web-based Agents IDE can be used to create agents based on W3C WoTTD





Aspect #2:W3CWoTTD-based No-Code Development for Multi-agent Systems





Aspect #3: W3C WoTTD Negotiation

- Partners desire deploy services/things as late as possible for optimization of industrial edge ("Edge Orchestration")
- Usage of W3C WoTTD Templates (W3C WoTTD Version 1) and W3C WoTThing Models (W3C WoTTD Version 1.1) for permitting late binding of edge-orchestrated services
- IntellIoT Edge Orchestrator emits W3C WoT Thing Models (i.e., Thing Descriptions without protocol binding)
- Agents are programmed (using the Web IDE) against these Thing Models
- Deployed agents request services from Edge Orchestrator. EO supplies protocol-bound W3C WoTTD

Proposal:W3CWoTTD Negotiation

- Parameters of machine-learning systems (capabilities)
- Security parameters
- Any non-functional parameter of a service/thing can be used in this sense

Aspect #4:W3CWoTTD-based Journaling of Agent-Artifact Interactions

- Implementation of prototype for journaling of W3C WoTTD-based interactions in a distributed ledger
- Purpose: Monitoring, auditing, root-cause analysis, possibly payments
- Recording of concrete exchanged messages (according to TD-binding)
- Recording of the service descriptions that are effective at run time
- In IntellIoT implemented using a distributed ledger; any other (trusted) journaling infrastructure may be used

Aspect #5:W3C WoTTDs in the context of Affordance Theory

https://www.alexandria.unisg.ch/269015/

- Collaboration with the HyperAgents project
- Investigation of Affordance Theory in the context of the guidance of interactions of autonomous hypermedia clients

https://hyperagents.org/

- Introduction of **signifiers as a first-class abstraction** in Web-based MAS
- Differentiation between signifiers and affordances to allow run-time adaptation of exposed IDLs
 - Adapt to agent goals
 - Adapt to agent abilities (including cognitive abilities)

Same functionality, but advertised...

1 . . .

```
9 <#sig> a hmas:Signifier ;
10 hint:signifies <#close-gripper> ;
11 hint:recommendsAbility [ a prs:PRSAbility ] ;
  hint:recommendsAbility [ manu:OperatorAbility ] ;
12
   hint:recommendsContext <#env-context>, <#prs-context> .
13
14
15 <#prs-context> a hint:Context: sh:targetClass hmas:Agent ;
16 sh:property [ sh:path prs:hasDesire ;
    sh:minCount 1 ; sh:qualifiedMinCount 1 ;
17
    sh:qualifiedValueShape <#desire-shape> ] .
18
19
20 <#desire-shape> a sh:NodeShape :
   sh:class manu:PickAndPlace:
21
   sh:property [ sh:path prs:hasInputList
22
43
       ...].
44
45 <#item-shape> a sh:NodeShape ;
   sh:class manu:Item ;
46
   sh:property [ sh:path manu:hasLocation ;
47
     ...].
59
60
61 <#location-shape> a sh:NodeShape ;
   sh:class manu:Location :
62
             ...for Agents that are based on
the Procedural Reasoning System
  sh:property [ sh:path manu:inRangeOf ;
63
64
   sh:minCount 1 ;
    sh:hasValue ex:leubot ] .
65
```



- 1 @prefix pddl:
- 2 <http://www.cs.yale.edu/homes/dvm/daml/pddlonto.daml#>.
- 3 . . .
- 9 <#sig> a hmas:Signifier ;
- 10 hint:signifies <#close-gripper> ;
- hint:recommendsAbility [11
- 12 a strips:StripsPlanningAbility] .
- 13
 - 14 <#close-gripper> a hint:ActionSpecification;
- 15 . . .
- 21 a a pddl:Action :
- pddl:action-label "closeGripper"; 22
- 23 pddl:parameters [a pddl:Param_seg ;
- rdf:_1 <#param1>]; 24
- 25 pddl:precondition [
- ...]: 31
- pddl:effect [32
- ...]. 41
- 42
- 43 <#param1> a pddl:Param ;
- pddl:name "?gv" : 44
- incorporate a STRIPS planner drs:type manu:GripperValue : 45
- :hasSchema <#gripper-schema> 46



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Drive Interoperability!

Enable **Decoupling**!

Enable Autonomy!

New W3C Community Group on Autonomous Agents on the Web (<u>https://www.w3.org/community/webagents/</u>)

IntellioT

Towards World-Wide Autonomous Systems

Autonomy of different components in IoT systems is becoming more and more relevant across domains!

Traditionally fragmented communities (Web of Things, Web Architecture, Autonomous Agents, Multiagent Systems, Semantic Web)

Dagstuhl Seminar and new W3C Community Group on Agents on the Web integrates these communities

Let's join forces to drive interoperability and autonomous behavior on the Web of Things!

https://www.w3.org/community/webagents/

https://www.dagstuhl.de/en/seminars/seminar-calendar/seminar-details/23081

